Single-Phase, Integrated Heatsink Type SSR **SRH1 Series** [Top-Bottom Terminal]

Single-Phase, Integrated Heatsink Type SSR [Top-Bottom Terminal]

Features

• High heat dissipation efficiency with ceramic PCB and integrated heatsink

- Input Indicator (green LED)
- DIN rail mount or panel mount installation
- [Voltage input type] Zero cross turn-on, random turn-on models available
- [Current input type] Phase control and cycle control possible
 - Phase control (power equality division/phase equality division)
 - Cycle control (fixed cycle/variable cycle) Please read "Safety considerations" in operation





60A

Rated load current

[Current input type]

20A/30A

(G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets

Line-up

(I) SSRs / Powe

(A) Photoelectric Sensors

(C) Door/Area Sensors

(D) Proximity Sensors

(M) Tacho / Speed / Pulse Meters

(P) Switching Mode Power Supplies

(Q) Stepper Motors

(R) Graphic/ Logic Panels

Ordering Information

manual before using.

RH	1 - 1	2 1	5 - 1	N			
						Voltage input type	Current input type
				Version	N	Renewal	
			Function		No Mark	Zero cross turn-on	<u> </u>
					R	Random turn-on	_
					10	10A	<u> </u>
			Rated load current (resistive load)		15	15A	_
					20	20A	20A
						30A	30A
					40	40A	_
					60	60A	60A
		Rated	d load voltage		2	24-240VAC	100-240VAC
					4	48-480VAC	200-480VAC
					1	4-30VDC	
		Rated input			2	24VAC	_
			·		4	90-240VAC	
	Control pha	Control phase			Α	-	4-20mA
	· ·				1	Single-phase	
	Input/output terminal				No Mark	Top-Bottom terminal	
Item					SRH	1	egrated heatsink type)

XThis ordering information is only for reference. For ordering a specific model, check the ordering information of the model.

※For more information about models, refer to the [B-16 page for the voltage input type]

B-22 page for the current input type .

I-15 **Autonics**

Single-Phase, Integrated Heatsink Type SSR [Voltage Input Type]

■ Model

Model	Rated input voltage	Rated load voltage	Rated input current	Function
SRH1-1210-N	4-30VDC			
SRH1-2210-N	24VAC	10A		
SRH1-4210-N	90-240VAC			
SRH1-1215-N	4-30VDC			
SRH1-2215-N	24VAC	15A		
SRH1-4215-N	90-240VAC			
SRH1-1220-N	4-30VDC			
SRH1-2220-N	24VAC	20A		
SRH1-4220-N	90-240VAC		24-240VAC	Zero cross turn-on
SRH1-1230-N	4-30VDC		24-240 VAC	Zero cross turn-on
SRH1-2230-N	24VAC	30A		
SRH1-4230-N	90-240VAC			
SRH1-1240-N	4-30VDC			
SRH1-2240-N	24VAC	40A		
SRH1-4240-N	90-240VAC			
SRH1-1260-N	4-30VDC			
SRH1-2260-N	24VAC	60A		
SRH1-4260-N	90-240VAC			
SRH1-1410-N	4-30VDC	10A		Zero cross turn-on
SRH1-1410R-N	4-30VDC			Random turn-on
SRH1-2410-N	24VAC			Zero cross turn-on
SRH1-1415-N	4-30VDC			Zero cross turn-on
SRH1-1415R-N	4-30VDC	15A		Random turn-on
SRH1-2415-N	24VAC			Zero cross turn-on
SRH1-1420-N	4.20V/DC			Zero cross turn-on
SRH1-1420R-N	4-30VDC	20A		Random turn-on
SRH1-2420-N	24VAC		48-480VAC	Zero cross turn-on
SRH1-1430-N	4-30VDC		40-40UVAC	Zero cross turn-on
SRH1-1430R-N	4-3000	30A		Random turn-on
SRH1-2430-N	24VAC			Zero cross turn-on
SRH1-1440-N	4-30VDC			Zero cross turn-on
SRH1-1440R-N	4-3000	40A		Random turn-on
SRH1-2440-N	24VAC			Zero cross turn-on
SRH1-1460-N	4.30VDC			Zero cross turn-on
SRH1-1460R-N	4-30VDC	60A		Random turn-on
SRH1-2460-N	24VAC			Zero cross turn-on

■ Specifications

○ Input

Rated inp	out voltage range	4-30VDC	24VACrms∼ (50/60Hz)	90-240VACrms~ (50/60Hz)
Allowable	e input voltage range	4-32VDC==	19-30VACrms~ (50/60Hz)	85-264VACrms~ (50/60Hz)
Max. inpu	ut current	18mA	15mArms (24VACrms∼)	18mArms (240VACrms∼)
Pick-up v	roltage	Min. 4VDC==	Min. 19VACrms∼	Min. 85VACrms~
Drop-out	voltage	Max. 1VDC==	Max. 4VACrms \sim	Max. 10VACrms∼
Turn-on	Zero cross turn-on	Max. 0.5 cycle of load source + 1ms	Max. 2 cycle of load source + 1ms	Max. 2 cycle of load source + 1ms
time	Random turn-on	Max. 1ms		
Turn-off t	ime	Max. 0.5 cycle of load source + 1ms	Max. 2 cycle of load source + 1ms	Max. 2 cycle of load source + 1ms

I-16 Autonics

Single-Phase, Integrated Heatsink Type SSR [Voltage Input Type]

Output

Rated load vo	Itage range	24-240VACrms	√ (50/60Hz)							
Allowable load voltage range		24-264VACrms~ (50/60Hz)								
Rated load current	Resistive load (AC-51) ^{×1}	10Arms	15Arms	20Arms	30Arms	40Arms	60Arms			
Min. load curre	ent	0.15Arms	0.15Arms	0.2Arms	0.5Arms	0.5Arms	0.5Arms			
Max. 1 cycle s (60Hz)	surge current	160A	160A	250A	400A	500A	1000A			
Max. non-repe current (I2t, t=8		130A ² s	130A ² s	300A ² s	910A ² s	1000A ² s	4000A ² s			
Peak voltage	(non-repetitive)	600V								
Leakage curre	ent (Ta=25°C)	Max. 10mArms (240VAC~/60H	z)						
Output on volt (max. load cur	age drop [Vpk] rrent)	Max. 1.6V								
Static off state dv/dt 500V/µs										
Rated load vo	Itage range	48-480VACrms∼ (50/60Hz)								
Allowable load	d voltage range	48-528VACrms~ (50/60Hz)								
Rated load current	Resistive load (AC-51) ^{×1}	10Arms	15Arms	20Arms	30Arms	40Arms	60Arms			
Min. load curre	ent	0.5Arms	0.5Arms	0.5Arms	0.5Arms	0.5Arms	0.5Arms			
Max. 1 cycle surge current (60Hz)		300A	300A	300A	500A	500A	1000A			
Max. non-repetitive surge current (I²t, t=8.3ms)		350A ² s	350A ² s	350A ² s	1000A ² s	1000A ² s	4000A ² s			
Peak voltage (non-repetitive)		1200V (zero cross turn-on), 1000V (random turn-on)								
Leakage curre	ent (Ta=25°C)	Max. 10mArms (480VAC~/60Hz)								
Output on volt (max. load cur	age drop [Vpk] rrent)	Max. 1.6V								
	dv/dt	500V/us								

X1: AC-51 is utilization category at IEC60947-4-3.

General specifications

Dielectric strength (Vrms) Insulation resistance Indicator Vibration Mechanical Malfunction Mechanical	2500VAC 50/60Hz 1 min (input-output, input/output-case) Over 100MΩ (at 500VDC megger) (input-output, input/output-case) Input indicator: green LED 0.75mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 1 hour 0.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 10 min		
Indicator Vibration Mechanical Malfunction Mechanical	Input indicator: green LED 0.75mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 1 hour 0.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 10 min		
Vibration Mechanical Malfunction Mechanical	0.75mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 1 hour 0.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 10 min		
Vibration Malfunction Mechanical	0.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 10 min		
Malfunction Mechanical			
. Mechanical			
	300m/s² (approx. 30G) in each X, Y, Z direction for 3 times		
Shock Malfunction	100m/s² (approx. 30G) in each X, Y, Z direction for 3 times		
Environment Ambient temp	-30 to 80°C (in case of the rated input voltage 90-240VAC~: -20 to 70°C), storage: -30 to 100°C (The rated load current capacity is different depending on ambient temperature. Refer to " SSR Derating Curve'.)		
Ambient humi	45 to 85%RH, storage: 45 to 85%RH		
Input terminal connection	Min. 1×0.5mm ² (1×AWG20), max. 1×1.5mm ² (1×AWG16) or 2×1.5mm ² (2×AWG16)		
Output terminal connection	Rated load current 10A/15A/20A : Min. 1×0.75mm² (1×AWG18), max. 1×4mm² (1×AWG12) or 2×2.5mm² (2×AWG14) Rated load current 30A/40A/60A : Min. 1×1.5mm² (1×AWG16), max. 1×16mm² (1×AWG6) or 2×6mm² (2×AWG10) **Use wires compliant with load current capacity to connect to the terminal.		
Input terminal fixed torque	0.75 to 0.95N·m		
Output terminal fixed torque	Rated load current 10A/15A/20A: 1.0 to 1.35N·m Rated load current 30A/40A/60A: 1.6 to 2.2N·m		
Approval	C€ c % us		
Weight ^{*1}	 Rated load current 10A/15A/20A: approx. 298g (approx. 225g) Rated load current 30A/40A: approx. 500g (approx. 410g) Rated load current 60A: approx. 770g (approx. 680g) 		

X1: The weight includes packaging. The weight in parenthesis is for unit only.

(A) Photoelectric Sensors

(C) Door/Area Sensors

(D) Proximity Sensors

(G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets

(I) SSRs / Powe Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

I-17 **Autonics**

^{*}Environment resistance is rated at no freezing or condensation.

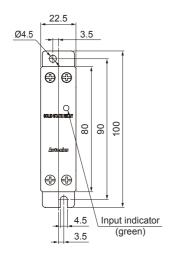
XFor wiring the terminal, round terminal must be used.

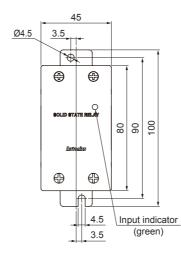
Dimensions

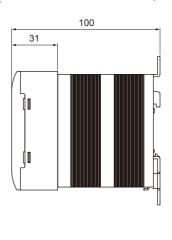
• Rated load current 10A/15A/20A

• Rated load current 30A/40A

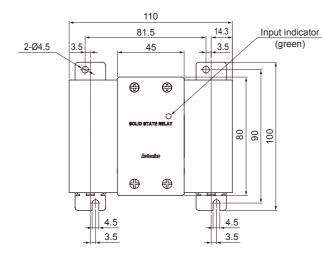
(unit: mm)

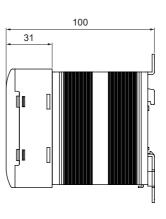






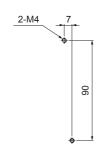
• Rated load current 60A



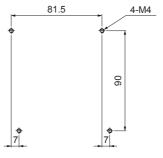


O Panel cut-out

• Rated load current 10A/15A/20A/30A/40A



Rated load current 60A

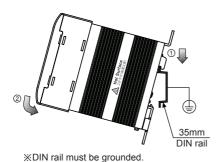


I-18 Autonics

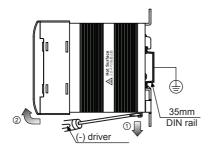
Single-Phase, Integrated Heatsink Type SSR [Voltage Input Type]

O DIN rail mounting

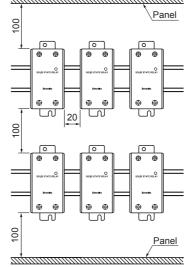
DIN rail attachment



DIN rail detachment



Spacing



*When installing multiple SSRs, please keep space between SSRs for heat radiation.

When installing SSRs horizontally (input part and output part on the same height), please supply less than 50% of the rated load current.

High temperature caution

While supplying power to the load or right after turning off the power of the load, do not touch the body and heat sink.

Failure to follow this instruction may result in a burn due to the high temperature.

(unit: mm)

(A) Photoelectric Sensors

(C) Door/Area Sensors

(D) Proximity Sensors

(G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets

(I) SSRs / Powe

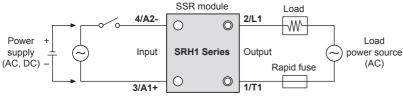
(M) Tacho / Speed / Pulse Meters

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

Connections



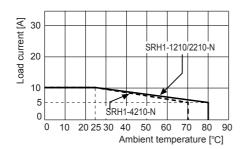
XUse terminals of size specified below.

ACCO CONTINUES OF CIEC OPPOSITOR DOLONI								
Terminal type		Input	Output					
Rated load current		10A, 15A, 20A, 30A, 40A, 60A	10A, 15A, 20A	30A, 40A, 60A				
= () ‡a b	а	Min. 3.5mm	Min. 4.0mm	Min. 5.0mm				
<round></round>	b	Max. 7.0mm	Max. 9.0mm	Max. 12.0mm				

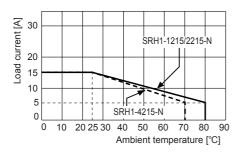
I-19 **Autonics**

■ SSR Derating Curve

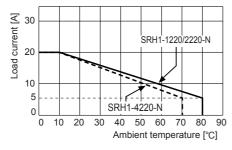
© SRH1-1210/2210/4210-N



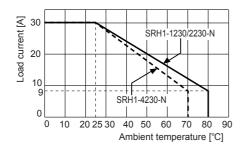
© SRH1-1215/2215/4215-N



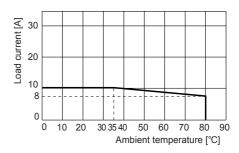
© SRH1-1220/2220/4220-N



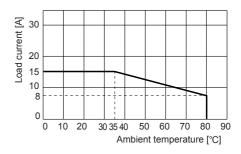
© SRH1-1230/2230/4230-N



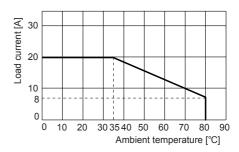
© SRH1-1410/1410R/2410-N



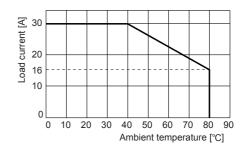
© SRH1-1415/1415R/2415-N



© SRH1-1420/1420R/2420-N



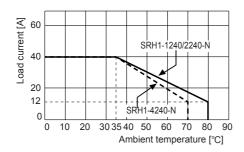
© SRH1-1430/1430R/2430-N



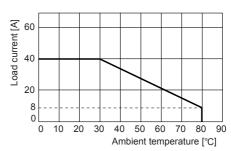
I-20 Autonics

Single-Phase, Integrated Heatsink Type SSR [Voltage Input Type]

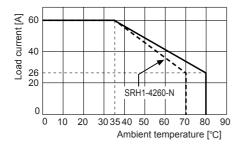
© SRH1-1240/2240/4240-N



© SRH1-1440/1440R/2440-N



SRH1-1260/1460/1460R-N SRH1-2260/2460/4260-N



∆ Since effectiveness of the heat radiation is decreased when multiple SSRs are installed closely, please supply less than 50% of the rated load current.

XAbove SSR derating curves obtained approval from the UL certification authority.

■ Proper Usage

⚠ Cautions during use

- 1. Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected accidents.
- 2. 4-30VDC, 24VAC signal input should be insulated and limited voltage/current or Class 2, SELV power supply device.
- 3. Install the unit in the well ventilated place.
- 3. Ground to the heat sink, panel, or DIN rail. Failure to follow this instruction may result in electric shock.
- 4. Ground to the panel. Failure to follow this instruction may result in electric shock.
- 5. While supplying power to the load or right after turning off the power of the load, do not touch the body and heat sink. Failure to follow this instruction may result in a burn due to the high temperature.
- 6. In order to protect the product from the short-circuit current of the load, use rapid fuse of which I²t is under the 1/2 of SSR I²t. When short-circuited, replace the fuse to those of same specification with the used rapid fuse.
- 7. Install dummy resistance in parallel with the load, to keep the sum of current flowing in the load and dummy resistance being over SSR minimum load current.
- 8. When using random turn-on model for phase control, install noise filter between the load and the power of the load.
- 9. Do not use near the equipment which generates strong magnetic force or high frequency noise.
- 10. This unit may be used in the following environments.
 - ① Indoors (in the environment condition rated in 'Specifications')
 - ② Altitude max. 2,000m
 - ③ Pollution degree 2
 - 4 Installation category III

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

> (C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure Sensors

> (F) Rotary

(G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets

(H) Temperature Controllers



Counters

<) imers

Panel Meters

(M) Tacho / Speed / Pulse Meters

> isplay nits

O) ensor ontrollers

(P) Switching Mode Power Supplies

(Q) Stepper Motors

& Drivers & Controllers

(R) Graphic/ Logic Panels

Field Network Devices

> T) Software

Autonics I-21

Single-Phase, Integrated Heatsink Type SSR [Current Input Type]

■ Model

Model	Rated input current		Rated load voltage	Model			Rated load voltage
SRH1-A220-N		20A		SRH1-A420-N		20A	
SRH1-A230-N	4-20mA	30A	100-240VAC	SRH1-A430-N	4-20mA	30A	200-480VAC
SRH1-A260-N		60A		SRH1-A460-N		60A	

Specifications

O Input

Rated input current	4-20mA
Max. allowable input current	50mA
Pick-up current	Min. 4.2mA
Static off current	Max. 4.0mA
Power factor	Min. 0.9 (max. 25° of difference between voltage phase and current phase)
Start-up time	60Hz: 200ms, 50Hz: 250ms
Operation time	60Hz: 16.6ms, 50Hz:20ms
Operation mode ^{*1}	Phase control (phase equality division type, power equality division type) Cycle control (fixed cycle, variable cycle)

X1: You can change operation mode by jumper pin. Default is Phase control (Power equality division type).

Output

Rated load voltage range		100-240VACrms~ (50/60Hz)			200-480VACrms∼ (50/60Hz)		
Allowable load	voltage range	90-264VACrms~ (50/60Hz)			200-528VACrms~ (50/60Hz)		
	Resistive load (AC-51) ^{×1}	20Arms	30Arms	60Arms	20Arms	30Arms	60Arms
Min. load curre	ent	0.5Arms			0.5Arms		
Max. 1 cycle surge current (60Hz)		300A	500A	1000A	300A	500A	1000A
Max. non-repetitive surge current (I ² t, t=8.3ms)		350A ² s	1000A ² s	4000A ² s	350A ² s	1000A ² s	4000A ² s
Peak voltage (n	on-repetitive)	600V			1000V		
Leakage current (Ta=25°C)		Max. 10mArms (240VAC~/60Hz)			Max. 10mArms (480VAC~/60Hz)		
Output on voltage drop[Vpk] (Max. load current) Max. 1.6V							
Static off-state dv/dt 500V/µs							

X1: AC-51 are utilization category at IEC60947-4-3.

General specifications

Phase control						
(phase equality division type)		5 to 99%				
Phase control		10 to 99%				
(power equalit	y division type)	10 10 33 %				
Frequency rea	ading function	Yes				
Dielectric strei	ngth (Vrms)	4000VAC 50/60Hz for 1 min (input-output, input/output-case)				
Insulation resi	stance	Over 100MΩ (at 500VDC megger)				
Indicator		Input indicator: green LED				
Vibration		0.75mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 1 hour				
	Ambient temp.	-20 to 70°C, storage: -20 to 100°C				
Environment	7 tiribiciti terrip.	(The rated load current capacity is different depending on ambient temperature. Refer to 🗉 SSR Derating Curve'.)				
	Ambient humi.	45 to 85%RH, storage: 45 to 85%RH				
Input terminal	connection	Min. 1×0.5mm ² (1×AWG20), max. 1×16mm ² (1×AWG6) or 2×1.5mm ² (2×AWG16)				
Output termina	al connection	Min. 1×1.5mm ² (1×AWG16), max. 1×16mm ² (1×AWG6) or 2×6mm ² (2×AWG10)				
Output terriiri	ai connection	XUse wires compliant with load current capacity to connect to the terminal.				
Input terminal	fixed torque	0.75 to 0.95N·m				
Output terminal fixed torque		1.6 to 2.2N·m				
Approval		20 ∠PR 3 ∋)				
Unit weight		Rated load current 20A/30A: Approx. 410g				
Offic weight		Rated load current 60A: Approx. 680g				

XEnvironment resistance is rated at no freezing or condensation.

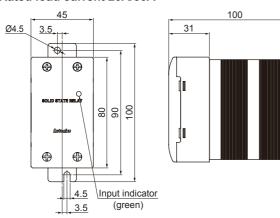
I-22 Autonics

[%]For wiring the terminal, round terminal must be used.

Single-Phase, Integrated Heatsink Type SSR [Current Input Type]

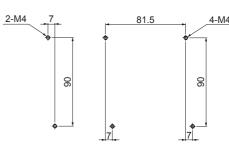


Rated load current 20A/30A



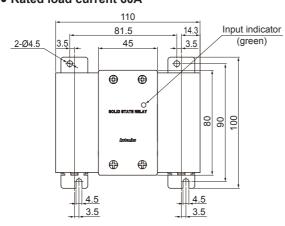
O Panel cut-out

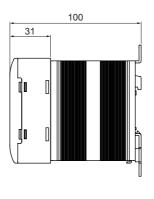
Rated load current
 Rated load current
 60A



% Screw tightening torque for mounting: 1.8 to 2.5N·m

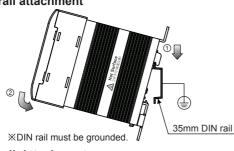
Rated load current 60A





O DIN rail mounting

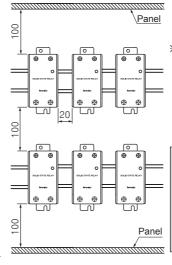
DIN rail attachment



• DIN rail detachment

| State of the content of th

Spacing



When installing multiple SSRs, please keep space between SSRs for heat radiation. When installing SSRs horizontally (input part and output part on the same height), please supply less than 50% of the rated load current.

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When installing multiple SSRs horizontally supply sup

High temperature caution

While supplying power to the load or right after turning off the power of the load, do not touch the body and heat sink. Failure to follow this instruction may result in a burn due to the high temperature.

(unit: mm) (A)
Photoelectric Sensors

(B) Fiber

(C) Door/Area Sensors

(D) Proximity Sensors

(E)

Sensors

(F) Rotary Encoders

(G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets

(H) Temperature Controllers

(I) SSRs / Power Controllers

(J)

(K)

L) Panel

(M) Tacho / Speed / Pulse

(N) Display Units

> o)) ensor entrollers

(P) Switching Mode Power Supplies

(Q) Stepper Motors

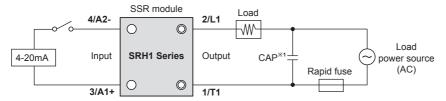
(R) Graphic/ Logic Panels

(S) Field Network Devices

T) Software

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Connections



X1: When connecting noise filter and capacitor, it is appropriate for EMC.

CAP: Rated load voltage 100-240VAC → 1uF/250VAC

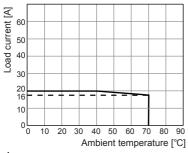
Rated load voltage 200-480VAC → 0.47uF/500VAC

XUse terminals of size specified below.

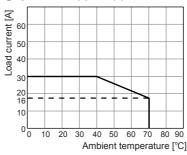
Terminal type		Input	Output
□ ↓a b	а	Min. 3.5mm	Min. 5.0mm
<round></round>	b	Max. 7.0mm	Max. 12.0mm

SSR Derating Curve

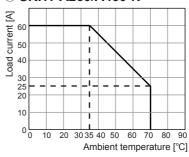
© SRH1-A220/A420-N



SRH1-A230/A430-N



SRH1-A260/A460-N



XAbove SSR derating curves obtained approval from the UL certification authority.

Operation Setting

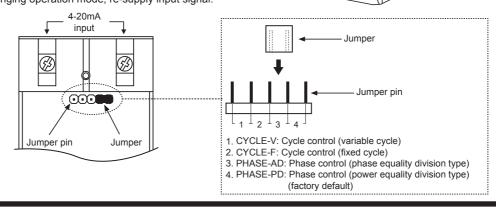
• Detach front cover

Press front cover connection 4 parts at right and left side with (-) driver, and front cover is detached. XBefore detaching front cover, you must cut off load

(-) driver

• Jumper pin setting

Operation mode is decided by jumper position. After changing operation mode, re-supply input signal.



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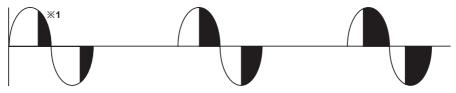
Single-Phase, Integrated Heatsink Type SSR [Current Input Type]

Operation Mode

O Phase control

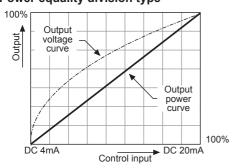
• Output waveform of phase control

When control input signal is 25%
 When control input signal is 50%
 When control input signal is 75%



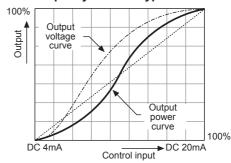
X1: The black parts of output waveform are output on the load.

• Power equality division type



Controls output power which is proportional to control input (4-20mA) level.

• Phase equality division type



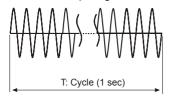
Controls phase angle which is proportional control input (4-20mA) level.

O Cycle control

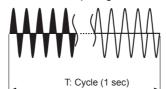
• Fixed cycle

Controls continuously the number of full cycle which is supplied to load every 1 sec by being proportional to control input (4-20mA).

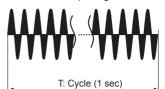
· When control input signal is 0%



· When control input signal is 50%



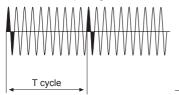
When control input signal is 100%



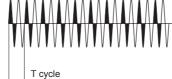
Variable cycle

Controls fast and accurately the subject with optimized the number of AC voltage cycle which is supplied to load by being proportional to control input (4-20mA).

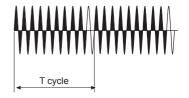
When control input signal is 10%



· When control input signal is 50%



When control input signal is 90%



(A) Photoelectric Sensors

(B) Fiber Optic Sensors

> (C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure Sensors

> (F) Rotary Encoders

(G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets

Temperature Controllers



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(M) Tacho / Speed / Pulse Meters

(N) Display

(O) Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

(S) Field Network Devices

(T) Software

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Proper Usage

- 1. Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected accidents.
- 2. Install the unit in the well ventilated place.
- 3. Ground to the heat sink, panel, or DIN rail. Failure to follow this instruction may result in electric shock.
- 4. While supplying power to the load or right after turning off the power of the load, do not touch the body and heat sink. Failure to follow this instruction may result in a burn due to the high temperature.
- 5. In order to protect the product from the short-circuit current of the load, use rapid fuse of which I²t is under the 1/2 of SSR I²t. When short-circuited, replace the fuse to those of same specification with the used rapid fuse.
- 6. Install dummy resistance in parallel with the load, to keep the sum of current flowing in the load and dummy resistance being over SSR minimum load current.
- 7. Do not use near the equipment which generates strong magnetic force or high frequency noise.
- 8. This unit may be used in the following environments.
 - ① Indoors (in the environment condition rated in 'Specifications')
 - ② Altitude max. 2,000m
 - 3 Pollution degree 2
 - 4 Installation category III

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